Non-uniform grid coarsening applied on explicit fracture modeling

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Non-uniform grid coarsening applied on explicit fracture modeling

- We want to determine a coarse grid suitable for saturation simulations that preserves important characteristics of the flow.
- Investigate two coarsening strategies: Non-uniform coarsening and Explicit fracture-matrix separation.

Key ideas:

- Velocity computed on a fine grid which resolves the fractures
- Saturation computed on the coarse grid



Heterogeneous model with 100 fractures





Two parameters:

 V_{\min} : Minimum volume of a coarse block G_{\max} : Maximum flow through each coarse block

The most important points from the algorithm:

- Group cells of similar flow magnitude into coarse blocks
- Coarse blocks have to be connected collections of fine cells
- Avoid too small blocks
- Avoid too large blocks

Non-uniform coarsening algorithm



Step 1: Segment $\log |v|$ into N level sets.

Step 2: Combine small blocks (|B| < c) with a neighbor.



Merge B with less volume than V_{\min} with the neighbor that has velocity magnitude close to B.

Step 2: 44 blocks

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Non-uniform coarsening algorithm

Step 3: Refine blocks with too much flow $|B|g(B) > G_{max}$.



Step 3: 81 blocks

Step 4: Combine small blocks with neighboring blocks.



Repeat step 2. Step 4: 70 blocks



Non-uniform coarsening algorithm



Advantages of the non-uniform coarsening algorithm:

- Applicable to both structured and unstructured grids
- Robust with respect to degree of coarsening
- Robust with respect to well-placement

Aarnes, J.E. et al: 2007, "Coarsening of three-dimensional structured and unstructured grids for subsurface flow". *Adv. Water Resour:* **30**(11), 2177-2193.

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Explicit Fracture-Matrix Separation (EFMS)



Initial model: 100×100 grid cells, 50 fracture lines

- \bullet Step 1: Introduce an initial coarse grid, here 5×5
- Step 2: Separate fracture and matrix part
- Step 3: Split non-connected blocks

Disadvantage: Upscaling factor difficult to tune.



Water saturation equation for a water-oil system:

$$\phi \frac{\partial S}{\partial t} + \nabla \cdot (f_w v) = q_w$$

- First-order finite volume method discretization
- Fluxes are computed as upstream fluxes with respect to the *fine* grid fluxes on the coarse interfaces



Comparison of coarse grids: NUC, EFMS and Cartesian

Heterogeneous model with 100 fractures. Saturations solutions at 0.48 PVI.

NUC grid with 206 blocks



 20×20 Cartesian grid



EFMS grid with 236 blocks



Fine grid





Results of comparison



- NUC grid: consistently best accuracy.
- EFMS grid: reasonably accurate solutions for the homogeneous model.
- Coarse Cartesian grid: lower accuracy, smears out saturation profile.

High and low permeable fractures

Stochastically generated fractures: 20 low permeable and 100 high permeable fractures.

 $K_{\text{high perm frac}} > K_{\text{matrix}}$ and $K_{\text{low perm frac}} \ll K_{\text{matrix}}$. 25 simulations with different fracture distribution.







Mean water-cut errors for heterogeneous model



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Accuracy:

- Both coarsening algorithms give more accurate results than conventional coarse grids.
- EFMS: poor accuracy when flow is influenced by underlying heterogeneous structures.
- Applicability:
 - NUC:
 - Easy to tune upscaling factor.
 - Assumes no prior knowledge of fractures provided they are represented in the geomodel.
 - EFMS:
 - Difficult to control upscaling factor.
 - Assumes "fracture cells" are prescribed.



Thank you for your attention!

Questions?

http://www.sintef.no/GeoScale

