

# Multiscale Simulation of Highly Heterogeneous and Fractured Reservoirs

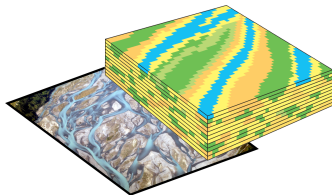
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Oslo, Norway

PETROMAKS  
Oslo, April 24–25, 2008

## Research group

- 3 researchers
- 4 postdocs
- 1–2 PhD students
- 3 programmers



Collaboration with national and international partners in industry and academia

## Research vision

Direct simulation of complex grid models of highly heterogeneous and fractured porous media — a technology that bypasses the need for upscaling.

<http://www.math.sintef.no/GeoScale/>

## Applications:

- Validation during development of geomodels
- Fast simulations of multiple realizations
- Optimization of production, well placement, etc
- History matching
- Geological storage of CO<sub>2</sub>

## Funding:

- Strategic research grant and PhD/postdoc grants
- Research grants with end-user involvement
- Industry projects

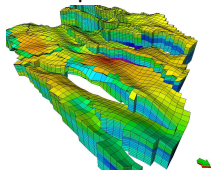
# Geological Models as Direct Input to Simulation

Complex reservoir geometries

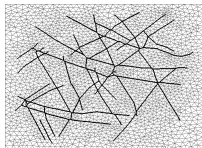
## Challenges:

- Industry-standard grids are often nonconforming and contain skewed and degenerate cells
- There is a trend towards unstructured grids
- Standard discretization methods produce wrong results on skewed and rough cells
- The combination of high aspect and anisotropy ratios can give *very large* condition numbers

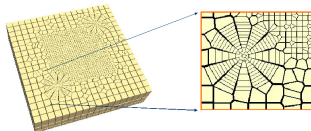
Corner point:



Tetrahedral:



PEBI:



**Aim:**

To develop a pressure solver with improved accuracy and flexibility.

**Solution:**

- use a mimetic finite difference method to improve accuracy and to reduce grid sensitivity
- use a multiscale method to balance speed and accuracy.

# Multiscale-streamline simulation of fractured reservoir

The mimetic method for reservoir simulation on polyhedral grids

Model:

$$\lambda_t^{-1} K^{-1} v + \nabla p = 0, \text{ (Darcy),}$$
$$\nabla \cdot v = q,$$

Seek discrete  $p$  and  $v$  that maintain

- mass balance
- a discrete form of Darcy's law

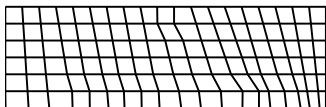
On polyhedral grids, the mimetic method yields exact solutions for linear pressure.

In fact, this is better than many commercial simulators!

# Multiscale-streamline simulation of fractured reservoir

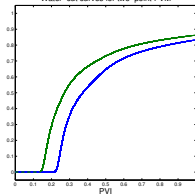
The mimetic method (cont'd)

Standard method + skew grids = grid-orientation effects

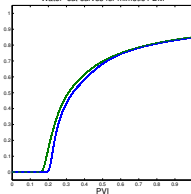


**K**: homogeneous and isotropic,  
symmetric well pattern  
→ symmetric flow

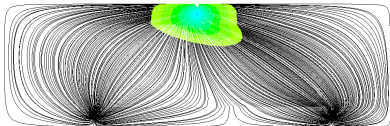
Water-cut curves for two-point FVM



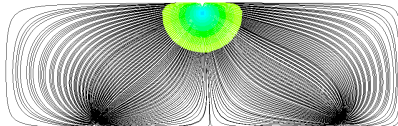
Water-cut curves for mimetic FDM



Streamlines with two-point method



Streamlines with mimetic method

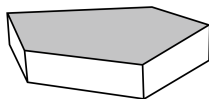


# Multiscale-streamline simulation of fractured reservoir

## The mimetic method (cont'd)

Mixed and mimetic formulation for one grid block:

$$\begin{bmatrix} B & C^T \\ C & \end{bmatrix} \begin{bmatrix} v \\ p \end{bmatrix} = \begin{bmatrix} -a \\ Q \end{bmatrix}$$



By eliminating  $v$  we get

$$CB^{-1}C^T p = Q + CB^{-1}a,$$

$$\text{MFEM: } B = \int_{\kappa} \phi_i \cdot \lambda^{-1} K^{-1} \phi_j d\Omega$$

$$\text{Mimetic: } B^{-1} = \lambda_t NKN^T - \text{tr}(K)(1 - UU^T)$$

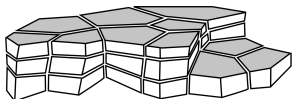


# Multiscale-streamline simulation of fractured reservoir

The mimetic method (cont'd)

Hybrid formulation:

$$\begin{bmatrix} B & C^T & D^T \\ C & & \\ D & & \end{bmatrix} \begin{bmatrix} v \\ p \\ a \end{bmatrix} = \begin{bmatrix} 0 \\ Q \\ 0 \end{bmatrix}$$

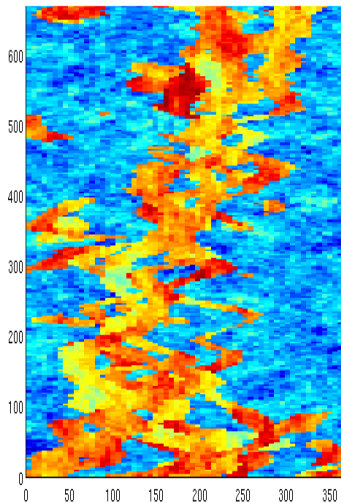
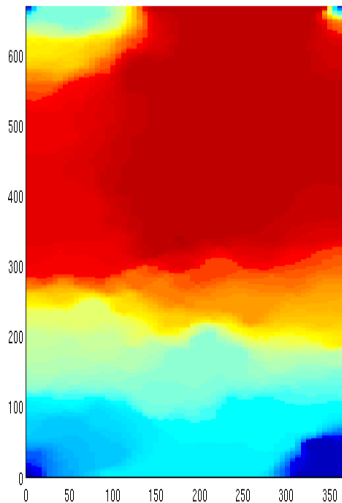


Elimination of  $p$  and  $v$  yields a positive definite system for  $a$ .

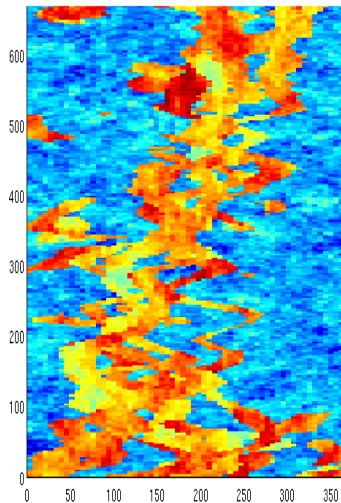
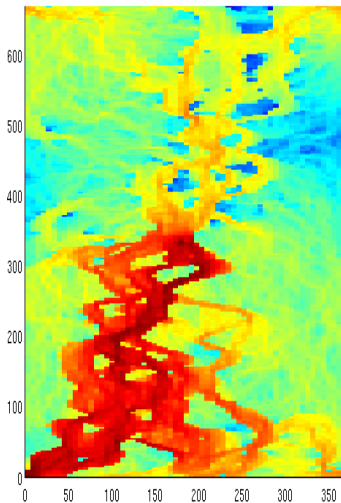
$$\text{MFEM: } B = \int_K \phi_i \cdot \lambda^{-1} K^{-1} \phi_j d\Omega$$

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Pressure typically varies smoothly while velocity is largely determined by local heterogeneities

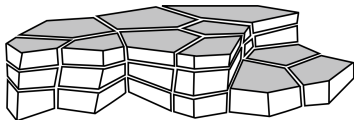


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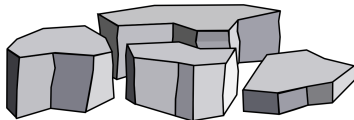


# The multiscale/mixed pressure solver framework

An efficient alternative to upscaling methods



Original simulation grid



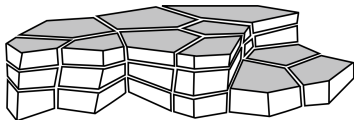
Partition into coarse grid

## Key Idea

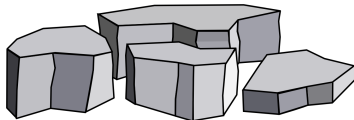
Express fluid flow in reservoir as a linear combination of local flow solutions on pairs of coarse grid blocks.

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# The multiscale/mixed pressure solver framework

An efficient alternative (cont'd)

- Local flows account for small-scale impact on global flow field
- Each localized flow field is obtained by resolving independent flow problems
- Any method may be used to discretize these problems

## End Result

High-resolution velocity field computable with comparatively few degrees of freedom (local problems resolved once or infrequently)

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## Current research problems

- Performance on compressible problems (i.e. with gas)
- Adapting coarse grid to placement of wells
- How to efficiently represent fractures on coarse grids
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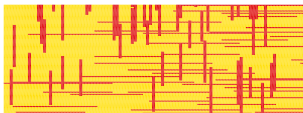
# Modeling of two-phase flow in fractured porous media on unstructured non-uniformly coarsened grids

- We want to determine a coarse grid suitable for saturation simulations that preserves important characteristics of the flow.
- Investigate two coarsening strategies: Non-uniform coarsening and Explicit fracture-matrix separation

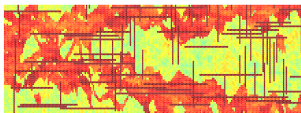
## Key ideas:

- Velocity computed on a fine grid which resolves the fractures
- Saturation computed on the coarse grid

Homogeneous model with 100 fractures



Heterogeneous model with 100 fractures



Two parameters:

$V_{\min}$ : Minimum volume of a coarse block

$G_{\max}$ : Maximum flow through each coarse block

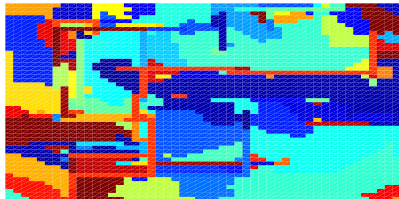
The most important points from the algorithm:

- Group cells of similar flow magnitude into coarse blocks
- Coarse blocks have to be connected
- Avoid too small blocks
- Avoid too large blocks

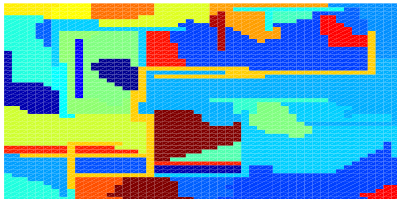


# Non-uniform coarsening algorithm

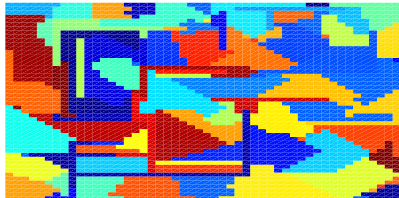
Coarse grid: Initial step, 152 cells



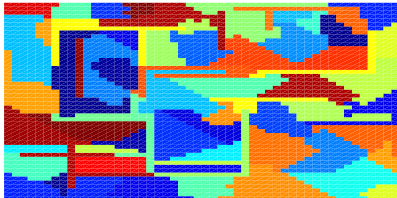
Coarse grid: Step 2, 47 cells



Coarse grid: Step 3, 95 cells

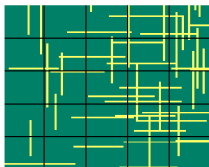


Coarse grid: Step 4, 69 cells

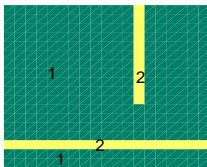


Note: Random coloring of blocks

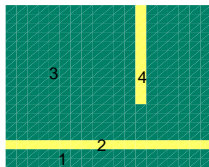
# Explicit Fracture-Matrix Separation (EFMS)



Step 1



Step 2



Step 3

Initial model:  $100 \times 100$  grid cells, 50 fracture lines

- Step 1: Introduce an initial coarse grid, here  $5 \times 5$
- Step 2: Separate fracture and matrix part
- Step 3: Split non-connected blocks

Disadvantage: Upscaling factor difficult to tune.

Water saturation equation for a water-oil system:

$$S_m = S_m \text{ at previous time step} + [\text{Flux in} - \text{Flux out}]$$

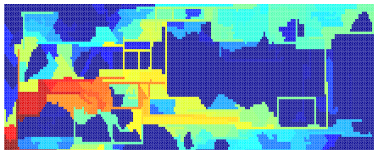
$S_m$  = water saturation in coarse grid block  $m$ .

- First-order finite volume method discretization
- Fluxes are computed as upstream fluxes with respect to the *fine* grid fluxes on the coarse interfaces

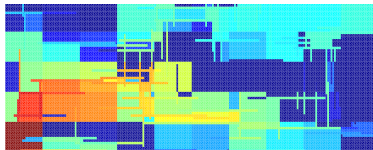
# Comparison of coarse grids: NUC, EFMS and Cartesian.

Heterogeneous model with 100 fractures  
Saturations solutions at 0.48 PVI.

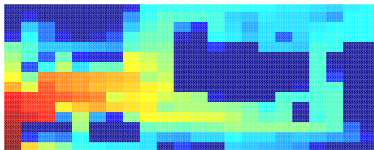
NUC grid with 206 blocks.



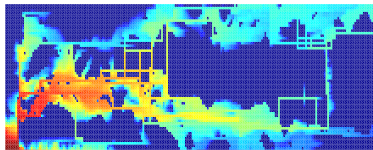
EFMS grid with 236 blocks.



20 × 20 Cartesian grid



Fine grid



- Capillary diffusion and gravity modeled on non-uniformly coarsened grids
- Compressible flow on non-uniformly coarsened grids
  - ⇒ Black-oil model on non-uniformly coarsened grids